

Univariate Non Linear Programming: Newton method



Univariate non linear optimization

Algorithm can be used for a *numerical* solution of the problem

These optimization algorithms generate a sequence of points converging to the optimal solution

There are two types of optimization algorithms:

- Dicotonomous (find the root of the equation of the derivative equal to zero and at each iteration reduce the search interval).
- We have seen the bisection method, another algorithm of this type is the secant method (explained in the exercise lecture).
- Approximation: these algorithms use local approximations of the function to be optimised



Termination criteria

- When to stop:
 - The solution is accurate with a given level of tolerance
 - Very small improvement from one iteration to the next: $|x_k - x_{k-1}| \le \varepsilon_x, \quad |f(x_k) - f(x_{k-1})| \le \varepsilon_f$
 - The maximum number of iterations has been reached
 - The solution diverges
 - The solutions are in a loop



Fit a quadratic approximation to f(x) using both gradient and curvature information at x.

• Use Taylor approximation:

 $f(x+h) = f(x) + f'(x)*h + \frac{1}{2} f''(x) h^2$

• Root finding of f '

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 $f'(x+h) = f'(x) + f''(x)h + o(h^2)$ Linear approximation $\Rightarrow h = -\frac{f'(x)}{f''(x)}$ • New guess: $x_{k+1} = x_k + h_k = x_k - \frac{f'(x_k)}{f''(x_k)}$



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• in practice, must be used with a globalization strategy which reduces the step length until function decrease is assured

Extension to N (multivariate) dimensions

□ How big N can be?

 problem sizes can vary from a handful of parameters to many thousands

